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Description. Robotics technology is currently deployed for carrying out multifaceted functions in the areas of fabrication and processing, particularly, in material handling, machine loading, welding, machining, inspection, etc. However, these commercial robots are stiff mechanical units with an elbow, a wrist and usually two fingers without any mobility and with no sense of feeling, hearing, and seeing.

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or process. Collaborative robots are designed to carry out the task in the same way a human would. More traditional industrial robots tend to carry out the task more efficiently than a human would. Robots That Are Not Automation

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A numerical-control machine tool is a good example of programmable automation. The program is coded in computer memory for each different product style, and the machine tool is controlled by the computer program. Industrial robots are another example. Flexible automation is an extension of programmable automation.

~~Manufacturing applications of automation and robotics~~

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will be useful to practising engineers and graduate students interested and engaged in research.

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